

Cascode Current Mirror

The main property/feature of a current source/sink is that the current through the device is independent of the voltage across it. Figure 1 shows the most basic of current sink. The current **I_{out}** is set by the voltage applied across the gate-source of the device, the greater the voltage the larger the current flow through the device. However as you can see from Figure 1 as the current increases then the slope in the saturation increases – for an ideal current sink/source we want this region to be flat ie very high resistance. These saturation slopes extrapolate to a point on the -x axis known as the Channel length modulation parameter λ , which is equal $1/\lambda$, typical values are 0.01-0.05. The smaller this value then the smaller the slope in saturation and the better the current source/sink will be.

The output resistance r_{out} is given by:-

$$r_{out} = \frac{1}{\lambda I_D}$$

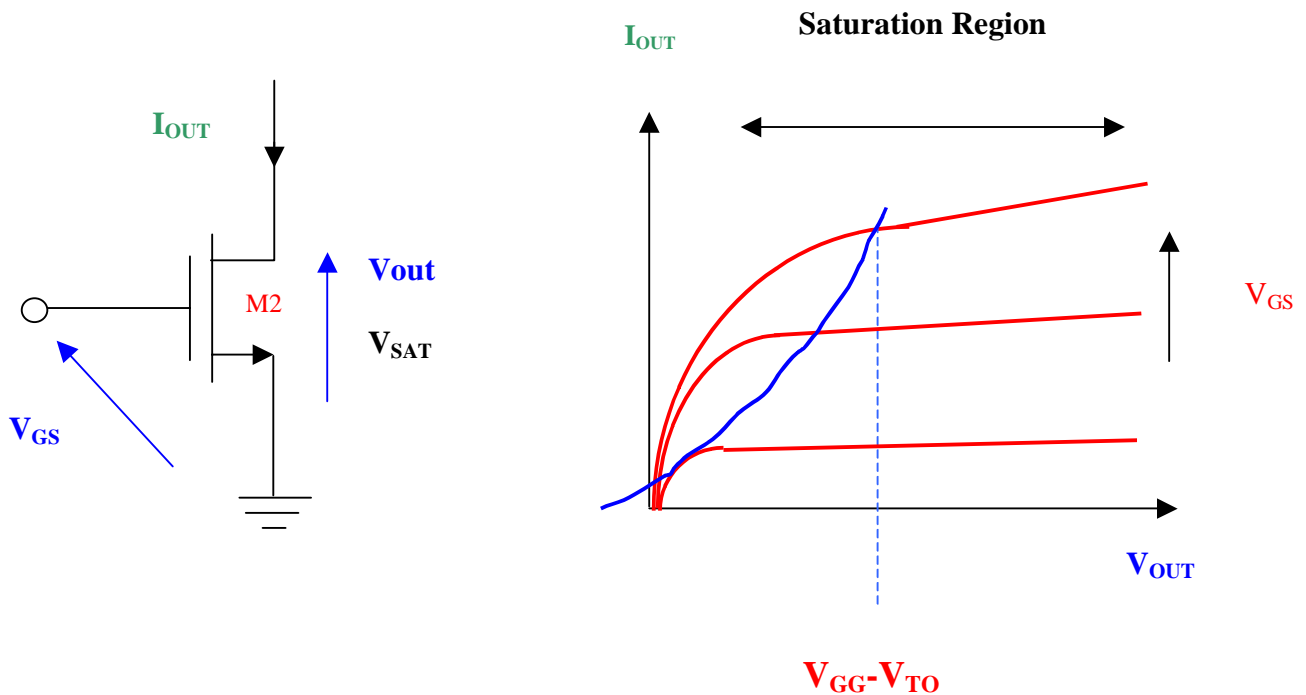


Figure 1 Simple current sink

As the slope in saturation region is determined by the output resistance r_{out} then increasing this will greatly improve the performance of the current source/sink. In addition we would like to reduce V_{sat} to allow larger voltage swings across the device.

One way of increasing the output resistance is to add a resistor between the source and ground as shown in Figure 2. In reality this method is not too practical because of the voltage drop across the resistor however, we can replace the resistor by an active resistor formed by a CMOS Fet and this forms the basis of the cascode current source/sink.

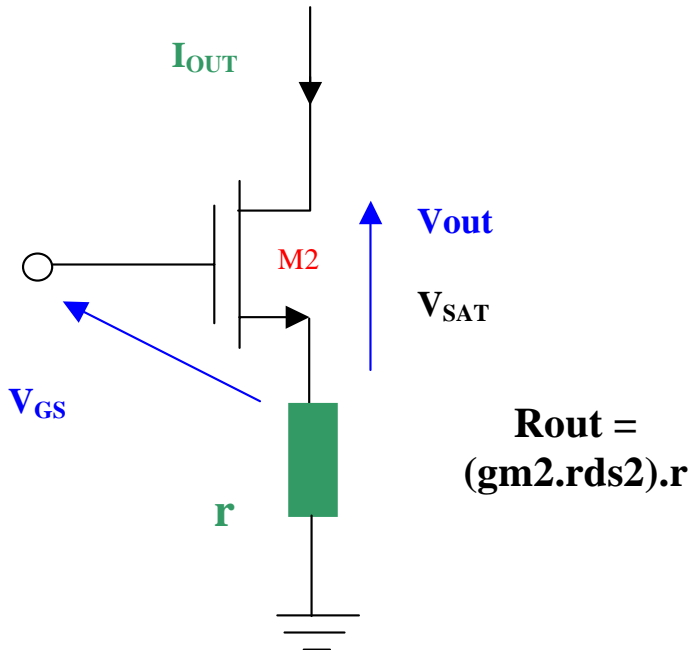


Figure 2 Method for increasing performance of current source/sink by adding a source resistor to increase rout by $(gm_2.r_{ds2}).r$.

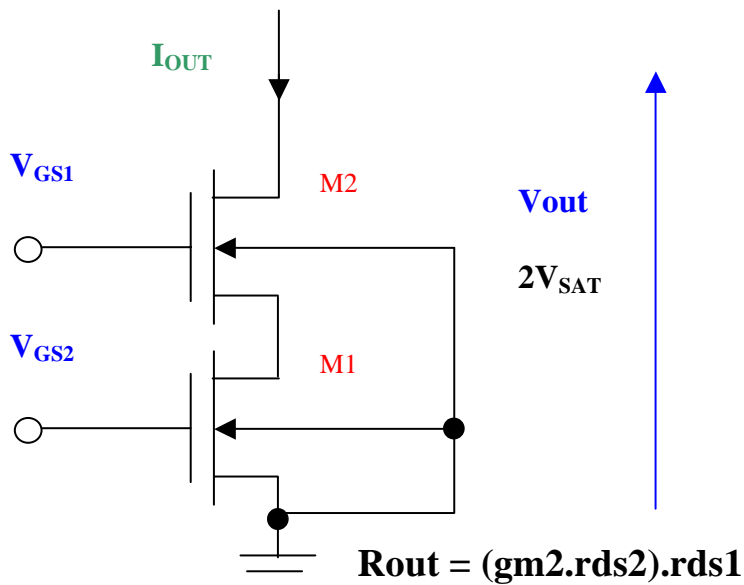


Figure 3 Adding an active load to increase the rout of the current source/sink to improve performance.

Figure 3 Shows the addition of an active load to M2 can increase the output resistance from r_{ds2} to $(g_{m2}.r_{ds2}).r_{ds1}$.

MOS Diode

When the gate and drain terminals are connected together on a CMOS FET the operation is similar to a p-n junction diode. The circuits for the n-type and p-type diode (active resistors) are shown in Figure 4.

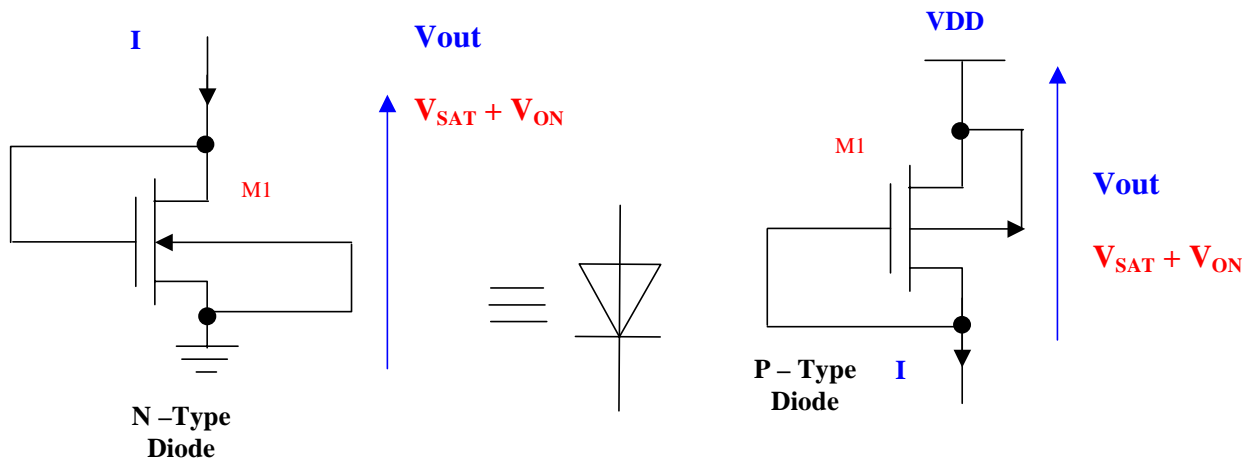


Figure 4 Active resistor/diode configurations. The gates are connected to the drains, and the sources are connected to supplies.

As used as an active load the resistance of the 'diode' is $1/g_m$.

$$I_D = \frac{\beta}{2}(V_{GS} - V_T)^2 \quad \text{Where } \beta = \frac{K'W}{2L}$$

As in the diode configuration the gate is connected to the source then $V_{GS} = V_{DS}$

and $I_D = \frac{\beta}{2}(V_{DS} - V_T)^2$ rearrange to get VDS

$$VDS = \sqrt{\frac{2I_D}{\beta}} + V_T$$

In most applications these diodes can be used to generate a fixed bias voltages as shown in Figure 5.

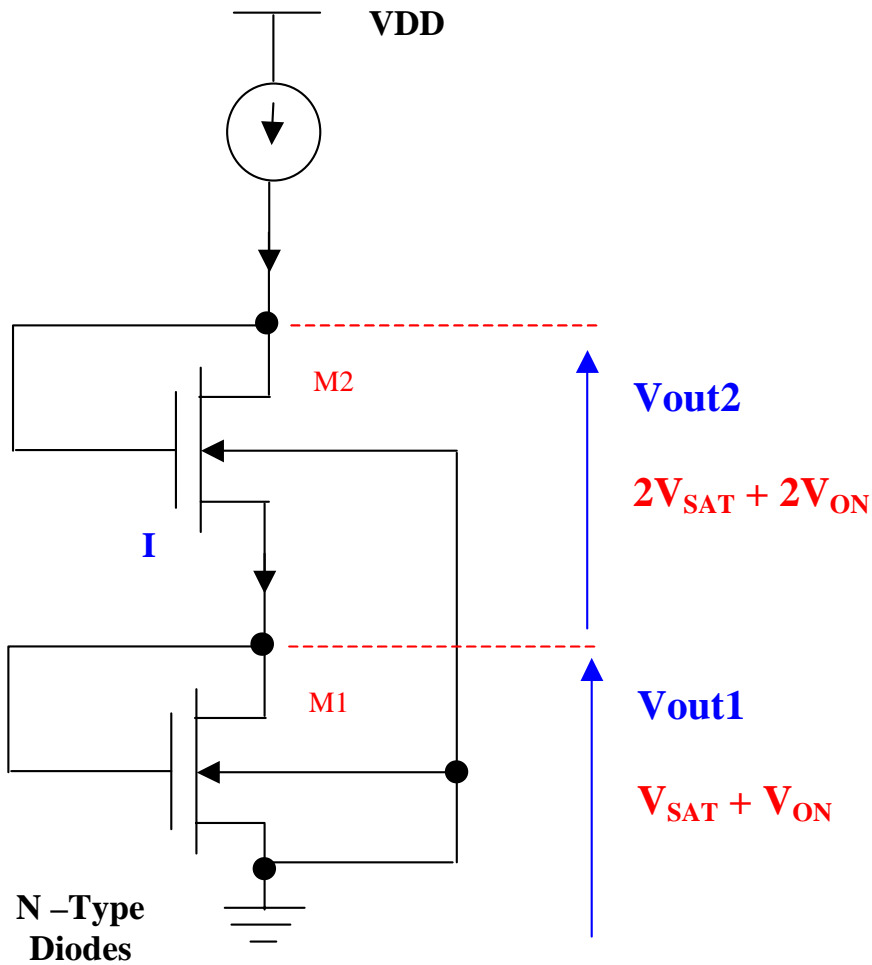


Figure 5 Two N-type CMOS diodes giving two fixed bias voltages of $V_{SAT}+V_{ON}$ and $2V_{SAT}+2V_{ON}$

We can use these CMOS diodes to provide bias to the current mirror shown in Figure 3 to form the most popular current source/sink circuits known as the **cascode** current mirror

M1 & M2 are effectively two diodes in series with a total voltage drop of $2V_{SAT}+2V_T$, which is fairly independent of current I_{REF} . I_{REF} can be set using a resistor or band-gap/resistor network.

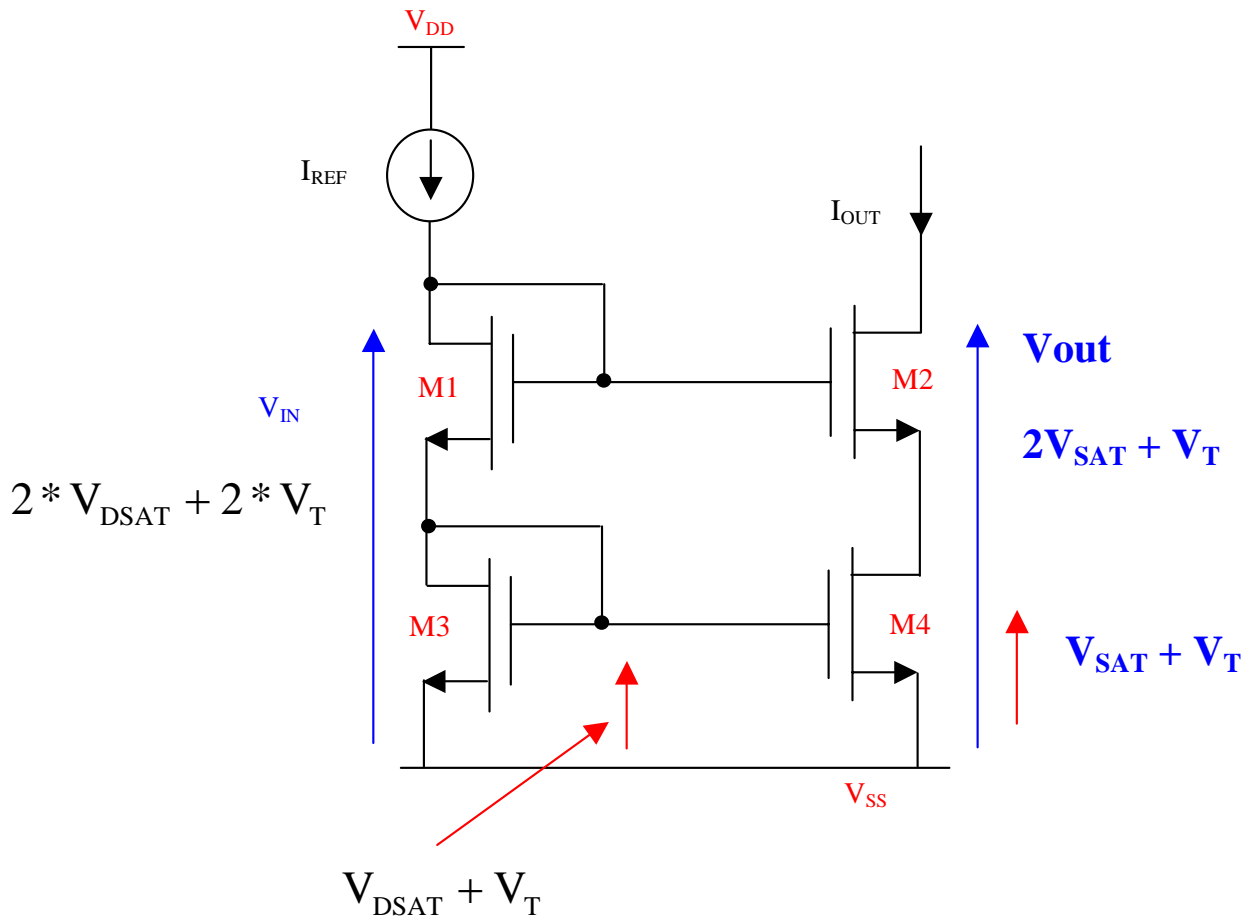


Figure 6 Cascode current source, showing that the minimum voltage output is $2V_{SAT}+V_T$ above the rail VSS (in this case 0V). M1 and M3 are wired as diodes and each have a voltage drop of $V_{SAT}+V_T$ across the drain-source junction.

This circuit has higher output impedance than the simple current mirror, but lower output swing due to the extra device.

$$V_D \geq V_G - V_T \quad - (1)$$

The bias to M2 (V_{gs2}) is $2V_{SAT} + 2V_T$ Sub into (1)

$$V_D \geq (2V_{SAT} + 2V_T) - V_T = 2V_{SAT} + V_T$$

$$R_{IN} = \frac{1}{gm_1} + \frac{1}{gm_3}$$

$$R_{OUT} = \frac{gm_2}{go_2 \cdot go_4} = gm \cdot r_{ds}^2$$

**Example**

Using the circuit of Figure 6, with $V_{DD} = +5V$ and $V_{SS} = -5V$. Assuming the following parameters $V_T = 1V$, $K_p = 80E-6$, $\lambda = 0.02$. Calculate V_{gs} , V_{out} and R_{out} . All FETs are the same ($W/L = 1$).

$$V_{gs} = V_T + \sqrt{\frac{I_{REF}}{K_p}} = 1 + \sqrt{\frac{20E^{-6}}{80E^{-6}}} = 1.5V$$

$$V_{SAT} = V_{GS} - V_T = 1.5 - 1 = 0.5$$

$$V_{out} = V_{SS} - (2V_{SAT} + V_T) = 5 - 2(0.5) + 1 = -3V$$

$$R_{OUT} = R_{O4} + R_{O2}(1 + gm_4.R_{O4})$$

$$gm = \frac{2.I_D}{V_{GS} - V_T} = \frac{2 * 20E^{-6}}{1.5 - 1} = 80E^{-6} A/V$$

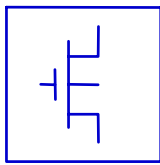
$$R_{O4} = R_{O2} = \frac{1}{\lambda.I_D} = \frac{1}{0.02 * 20E^{-6}} = 2.5M\Omega$$

$$\therefore R_{OUT} = 2.5E^6 + 2.5E^6(1 + 80E^{-6}.2.5E^6) = 505M\Omega$$

The above circuit with the data given was simulated in ADS using a DC simulation to verify the calculated results. The simulation setup is shown in Figure 7, for this setup the circuit was analysed and the **annotate DC solution** selected to add all the node voltage and currents to the circuit.



DC
DC1
SweepVar=
Start=0
Stop=5
Step=.01



LEVEL1_Mode
MOSFETM
NMOS=yes
Vto=1
Kp=80e-6
Lambda=LAMBDA

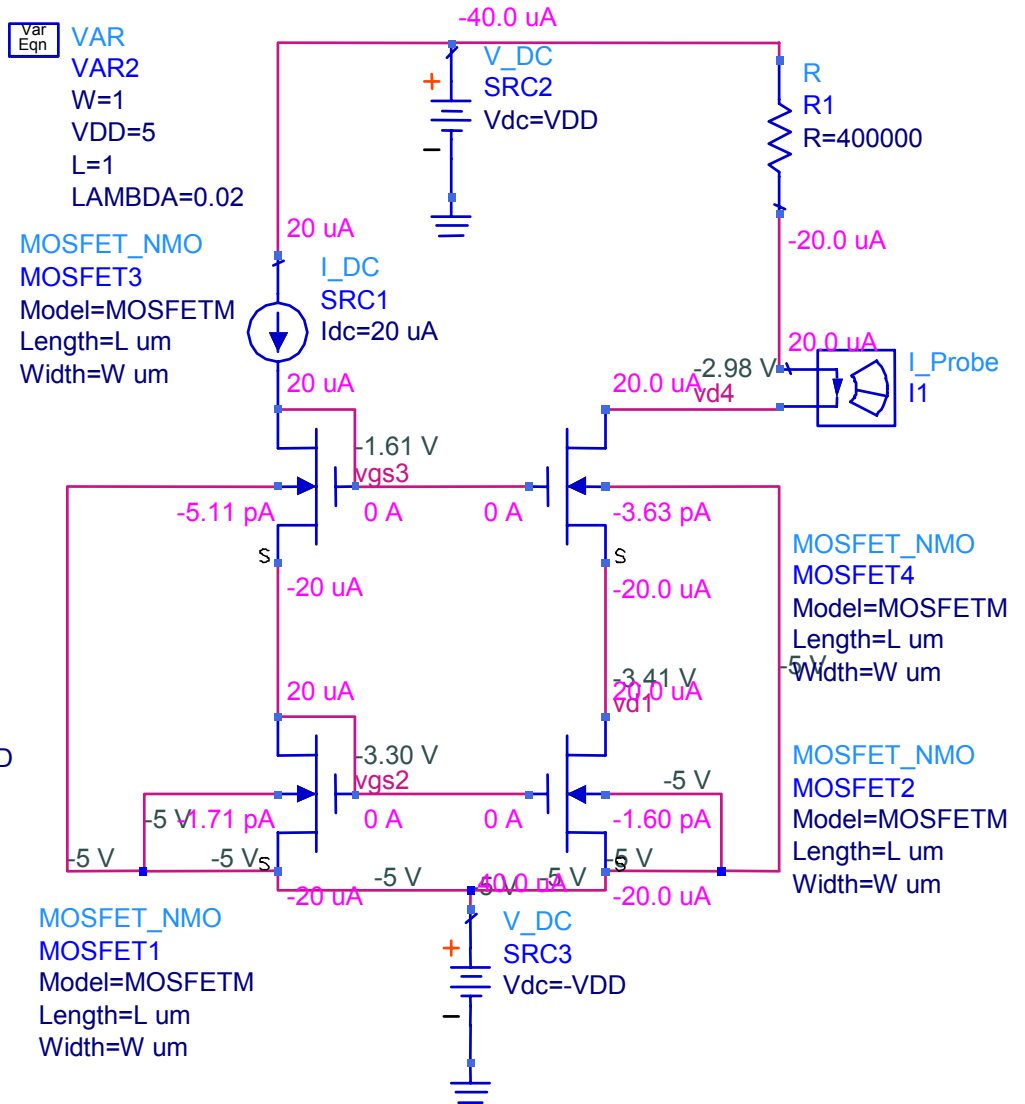


Figure 7 ADS DC simulation of the cascode current source example. The resistor load has been calculated assuming a current of 20uA and a Vout minimum of -3V. NOTE that the bulk connections have been connected to the lowest circuit potential ie -VDD or -5V. The simulation has given slightly different results from the simplified hand calculations as you would expect.



Decreasing V_{OUT}

A cascode current sink can be used in the 'tail' in a long-tail pair/differential amplifier to improve the common mode rejection. However, because we are using two stages the current mirror will reduce the rail voltage available by $V_{OUT} = 2V_{SAT} + V_T$, which could be typically $\sim 2V$ less than the supply rail. Other cascode circuits have been modified to reduce V_{OUT} as much as possible.

One such circuit is shown in Figure 8.

$$V_{GS} = V_{ON} + V_T$$

So rearranging $V_{ON} = V_{GS} - V_T$ is also $= V_{SAT}$

$$I_d = \frac{K'W}{2L}(V_{GS} - V_T)^2 \quad \text{we can sub in to get } I_d = \frac{K'W}{2L}(V_{ON})^2$$

$$\text{And } V_{ON} = \sqrt{\frac{2 \cdot I_d \cdot L}{K'W}}$$

If we set the W/L ratio of M1 to 0.25 then

$$V_{ON} = \sqrt{\frac{2 \cdot I_d \cdot 4W}{K'L}} = \sqrt{4} = 2 \cdot V_{ON}$$

Therefore, V_{GS1} is $V_T + 2V_{ON}$

$$V_D \geq V_G - V_T \quad - \quad (1)$$

To bias to M2 (V_{GS1}) is $2V_{SAT} + V_T$ Sub into (1)

$$V_D \geq (2V_{SAT} + V_T) - V_T = 2V_{SAT}$$

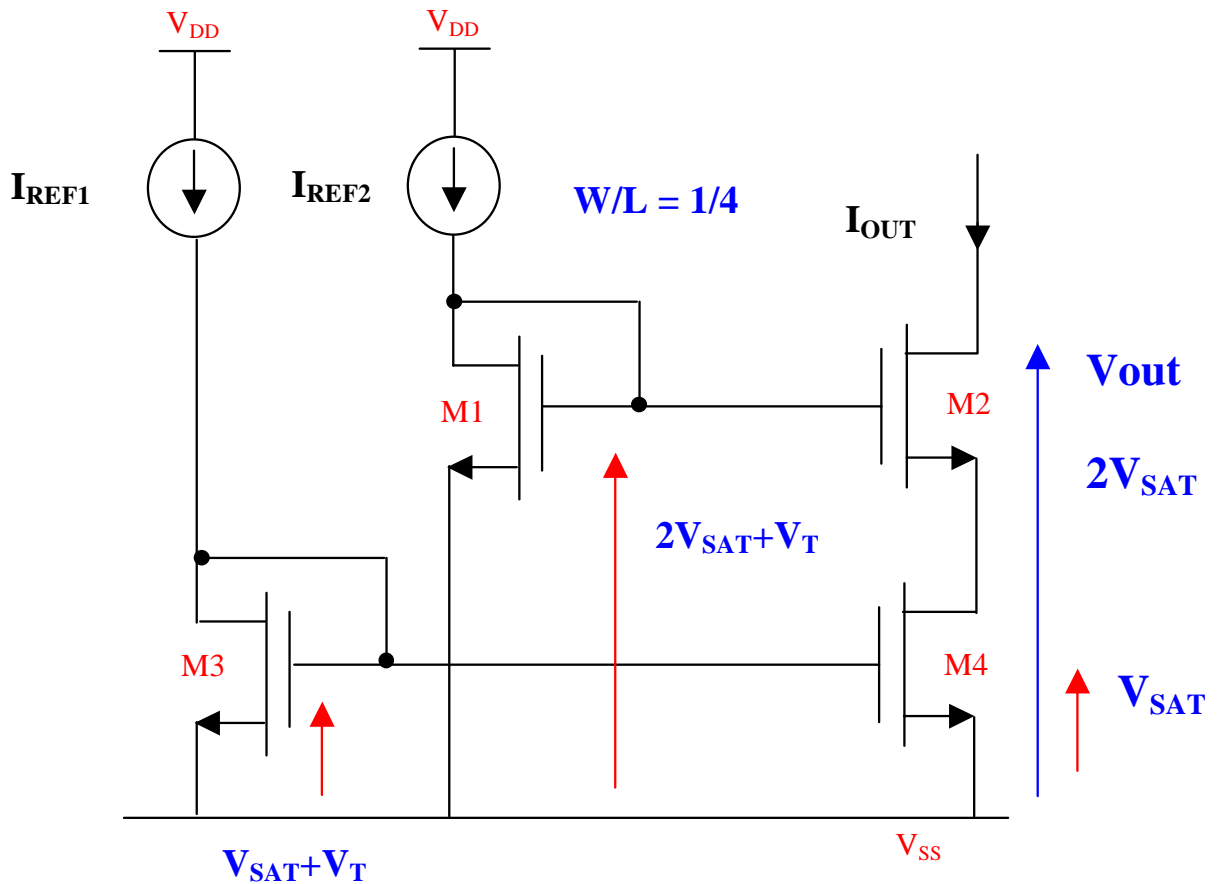


Figure 8 Method for decreasing the voltage drop across the two output devices to give a greater available voltage swing.

Although this circuit has a low output voltage drop ($2V_{ON}$) it suffers in that M1 connected to M2 are not matched devices (M1 has a W/L ratio of 0.25). As a result I_{OUT} will not track I_{REF} over temperature.

To eliminate this problem the circuit shown in Figure 9 is used.

Each pair of FETS in the cascode are fed with the same bias. M3 supplied $2V_{SAT} + V_T$ to the top pair FETS M4 and M5.

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